## **Amendments to the Claims:**

This listing of claims will replace all prior versions, and listings, of claims in the application:

## **Listing of Claims:**

Please cancel Claims 13-20. Please amend Claims 1, 7, 12, 21 and 22 as follows:

1. (Currently Amended) A tool comprising:

a tear-off edge;

a grasper adapted to selectively grasp a tearable medium;
a conveyor adapted to selectively move the grasper along an first axis
to move the tearable medium against a the tear-off edge to sever the tearable medium; and
a controller adapted to transmit a first signal for instructing the
conveyor to move the grasper and a second signal for instructing the grasper to grasp the
tearable medium.

(ゾク

(Original) The tool of claim 1, wherein the grasper comprises first and second jaws adapted to grasp the tearable medium therebetween.

9 3. (Original) The tool of claim 2, wherein the first jaw comprises a pad for frictionally engaging the tearable medium.

2 4. (Original) The tool of claim 1, wherein the controller comprises a programmable logic device.

(Original) The tool of claim, 2, wherein the grasper comprises an actuator adapted to move the first jaw into engagement with the tearable medium for grasping the tearable medium between the first and second jaws and to move the first jaw out of engagement with the tearable medium for releasing the tearable medium from between the first and second jaws.

(Original) The tool of claim 1, wherein the tear-off edge constitutes a part of a printer.

(Currently Amended) The tool of claim 2, wherein the first jaw is actuatable along an a second axis that forms an angle with the <u>first</u> axis along which the conveyor moves the grasper.

(Original) The tool of claim 1, wherein the controller receives a signal that instructs the controller to transmit the first and second signals.

9. (Original) The tool of claim 1, and further comprising an electromagnetical valve that receives the first signal from the controller, the electromechanical valve passing a flow of fluid to the conveyor upon receiving the first signal for moving the grasper.

/2 16. (Original) The tool of claim 2, and further comprising an electromechanical valve that receives the second signal, the electromechanical valve passing a flow of fluid to the grasper upon receiving the second signal for moving the first jaw into engagement with the tearable medium.

(Original) The tool of claim 1, wherein the conveyor comprises a carriage and at least one rail, the carriage slidably attached to the at least one rail and fixedly attached to the grasper.

/ 3 1/2. (Currently Amended) A tool comprising: a tear-off edge;

first and second jaws;

an actuator adapted to selectively move the first jaw along a first axis into engagement with a tearable medium to grasp the tearable medium between the first and second jaws and out of engagement with the tearable medium to release the tearable medium from between the first and second jaws;

a conveyor adapted to selectively move the first and second jaws along a second axis that forms an angle with the first axis to move the tearable medium when grasped by the first and second jaws against [a] the tear-off edge to sever the tearable medium; and



a controller adapted to transmit a first signal for instructing the conveyor to move the grasper from a first position, and a second signal for instructing the actuator to move the first jaw into engagement with the tearable medium.

13-20. Cancelled.

15 21. (Currently Amended) A tool for tearing printable media from an imaging device, the tool comprising:

a conveyor;

an actuator attached to the conveyor, the actuator <del>comprising</del> <u>including</u>: a slide;

a first jaw fixedly attached to the actuator;

a first jaw attached to the slide of the actuator;

a second jaw located opposite the first jaw and slidably attached to the slide of the actuator so as to linearly move towards and away from the first jaw; and a second jaw fixedly attached to the actuator and located opposite the first jaw;

a controller connected to the conveyor and the actuator.

jaw comprises a pad. (Currently Amended) The tool of claim 21, wherein the first second

17 23. (Original) The tool of claim 21, wherein the controller comprises a programmable logic device.

(Original) The tool of claim 21, and further comprising an electromechanical valve that is electrically connected to the controller and fluidly connected to the conveyor.

(Original) The tool of claim 2/1, and further comprising an electromechanical valve that is electrically connected to the controller and fluidly connected to the actuator.



26. (Original) The tool of claim 21, wherein the conveyor comprises a carriage and at least one rail, the carriage slidably attached to at least one rail and fixedly attached to the actuator.

(Original) The tool of claim 21, wherein the actuator is attached to the conveyor so that the slide of the actuator is oriented at an angle with respect to the conveyor.

Please add Claims 28-37 as follows:

28. (New) The tool of claim 1, wherein the tear-off edge extends along a second axis oblique to the first axis.

(New) The tool of claim 12, wherein the tear-off edge extends along a third axis oblique to the second axis.

27 36. (New) The printing system comprising:

a printer configured to print upon a tearable medium;

an edge configured to extend along the tearable medium;

a grasper configured to grasp the tearable medium while being moved to urge the tearable medium against the edge to sever the medium.

73 31. (New) The system of claim 30, wherein the edge extends along a first axis and wherein the grasper is movable along a second axis oblique to the first axis.

27 32. (New) The system of claim 30 including a conveyor configured to move the grasper.

(New) The system of claim 32 including an actuator configured to move the grasper between a grasping state in which the grasper grasps the tearable medium and a releasing state in which the grasper does not grasp the tearable medium.

- 24. (New) The system of claim 33 including a controller configured to generate control signals, wherein the conveyor moves the grasper in response to the control signals and wherein the actuator moves the grasper in response to the control signals.
- 35. (New) The system of claim 36 including an actuator configured to move the grasper between a grasping state in which the grasper grasps the tearable medium and a releasing state in which the grasper does not grasp the tearable medium.
- 25 36. (New) The system of claim 30, wherein the grasper includes a first surface and a second opposite surface and wherein the first surface and the second surface are configured to engage opposite sides of the tearable medium.
- New) The system of claim 26, wherein at least one of the first surface and the second surface is movable relative to the other of the first surface and the second surface to move between a grasping state and a releasing state.